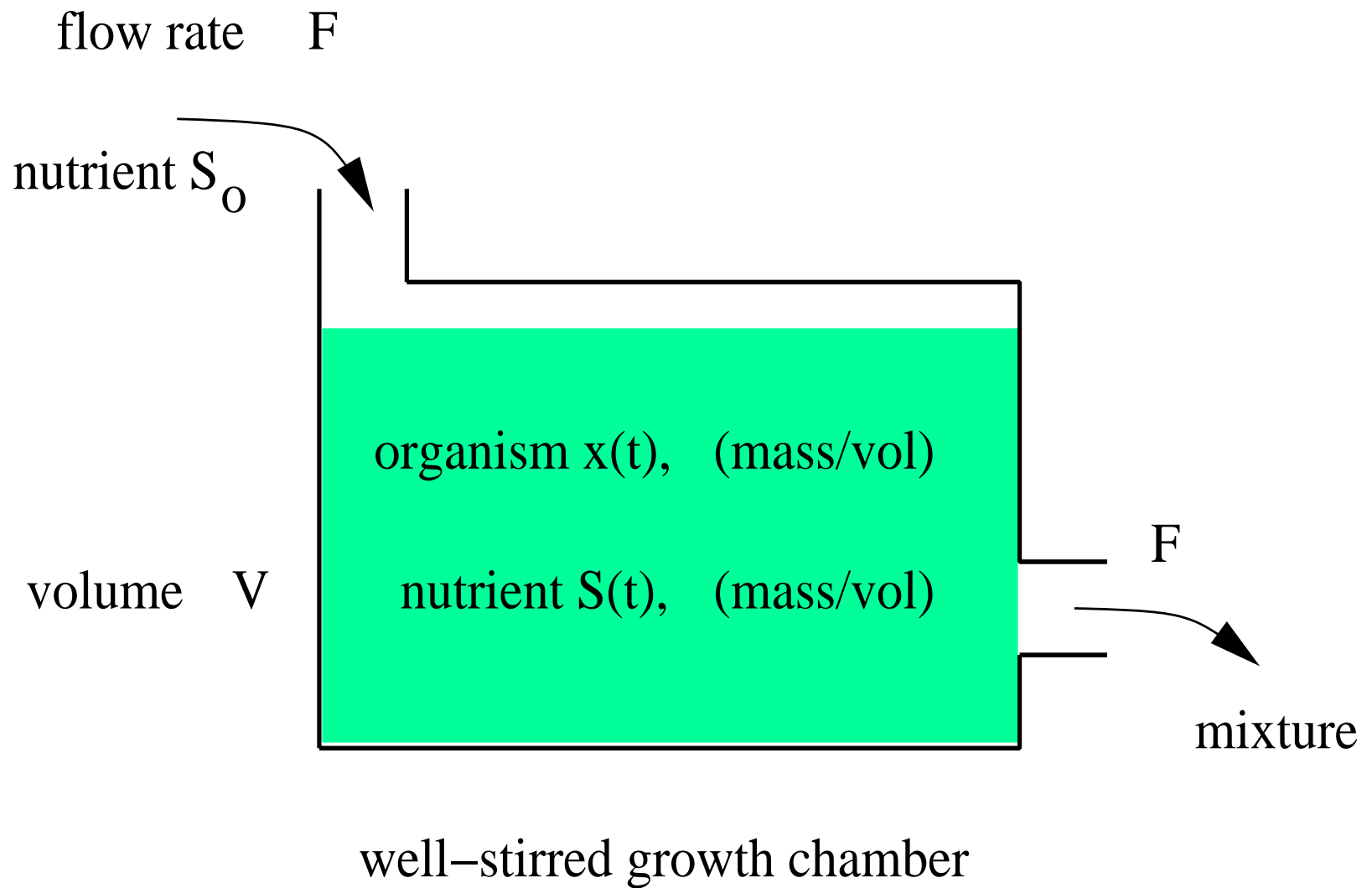


# Chemostat Model



$$dx/dt = \text{rate produced} - \text{rate out}$$

$$dS/dt = \text{rate in} - \text{rate out} - \text{rate consumed}$$

Let  $g(S)$  be the growth rate of the organism with units of 1/time and is an increasing function of nutrient. Let  $\gamma$  be the *yield* constant which is the mass of the organism produced per unit mass of nutrient, i.e.,

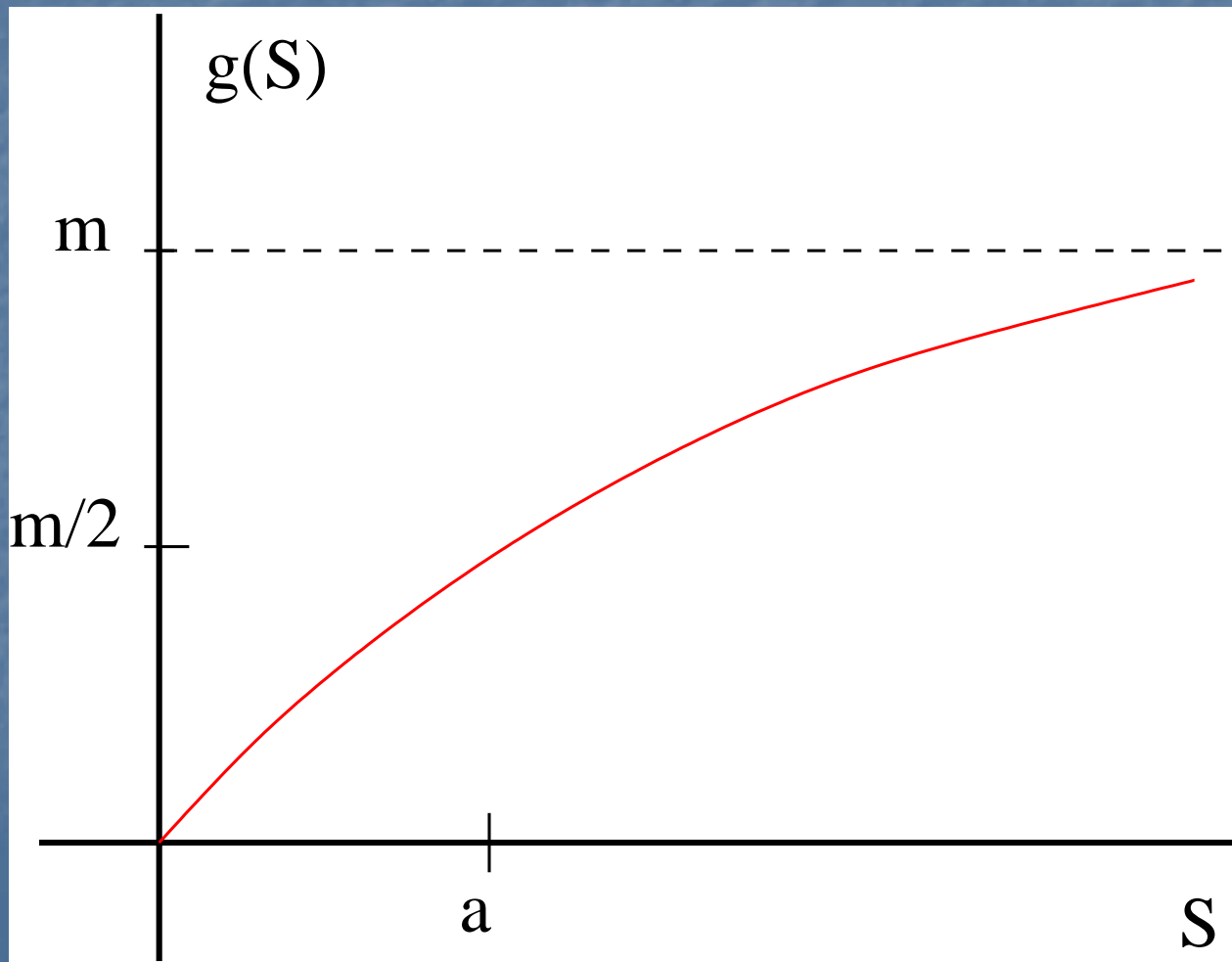
$$\gamma = \frac{\text{mass of organism produced}}{\text{mass of nutrient used}}.$$

Then the system of differential equations becomes:

$$\frac{dx}{dt} = g(S)x - \frac{F}{V}x$$

$$\frac{dS}{dt} = \frac{F}{V}S_0 - \frac{F}{V}S - \frac{1}{\gamma}g(S)x.$$

Assume  $g(S) = \frac{mS}{a+S}$ , a Monod or Michaelis-Menton saturation function, which means that the organism is limited in its ability to consume nutrient.  $m$  is the maximal growth rate (units 1/t) and  $a$  is the half-saturation constant (units mass/vol).



$$g(a) = m/2$$

Divide the first equation by  $\gamma$  and both equations by  $S_0 F/V$ :

$$\frac{V}{\gamma F S_0} \frac{dx}{dt} = \left[ \frac{m \frac{V}{F} \frac{S}{S_0}}{\frac{a}{S_0} + \frac{S}{S_0}} \right] \frac{x}{\gamma S_0} - \frac{x}{\gamma S_0}$$

$$\frac{V}{F S_0} \frac{dS}{dt} = \frac{S_0}{S_0} - \frac{S}{S_0} - \left[ \frac{m \frac{V}{F} \frac{S}{S_0}}{\frac{a}{S_0} + \frac{S}{S_0}} \right] \frac{x}{\gamma S_0} .$$

Scaling  $x$  by  $\gamma S_0$ ,  $S$  by  $S_0$  and  $t$  by  $V/F$  and replacing parameters  $a/S_0$  by  $a$  and  $mV/F$  by  $m$  gives:

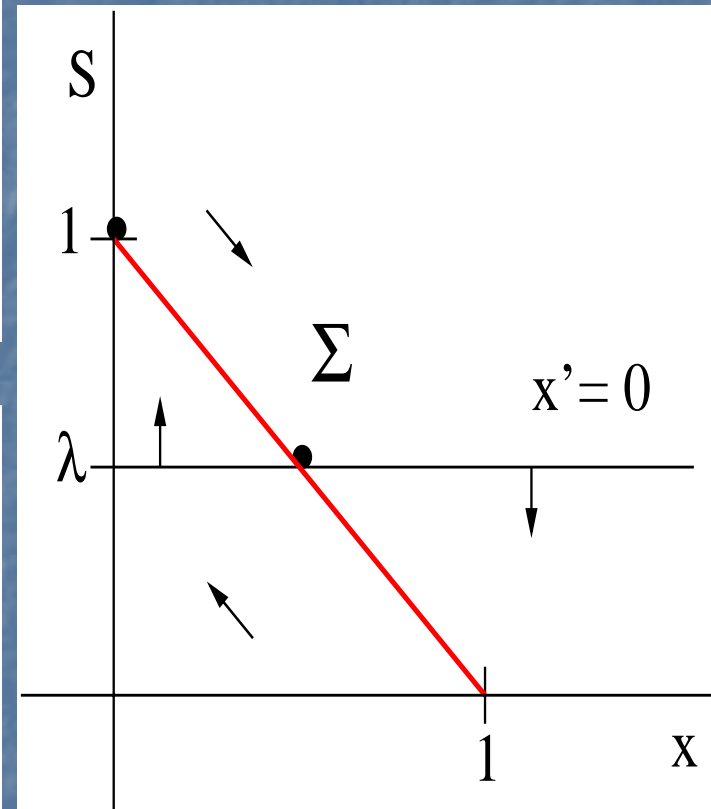
$$\frac{dx}{dt} = \left[ \frac{m S}{a + S} \right] x - x \tag{Ch}$$

$$\frac{dS}{dt} = 1 - S - \left[ \frac{m S}{a + S} \right] x .$$

# Model Analysis

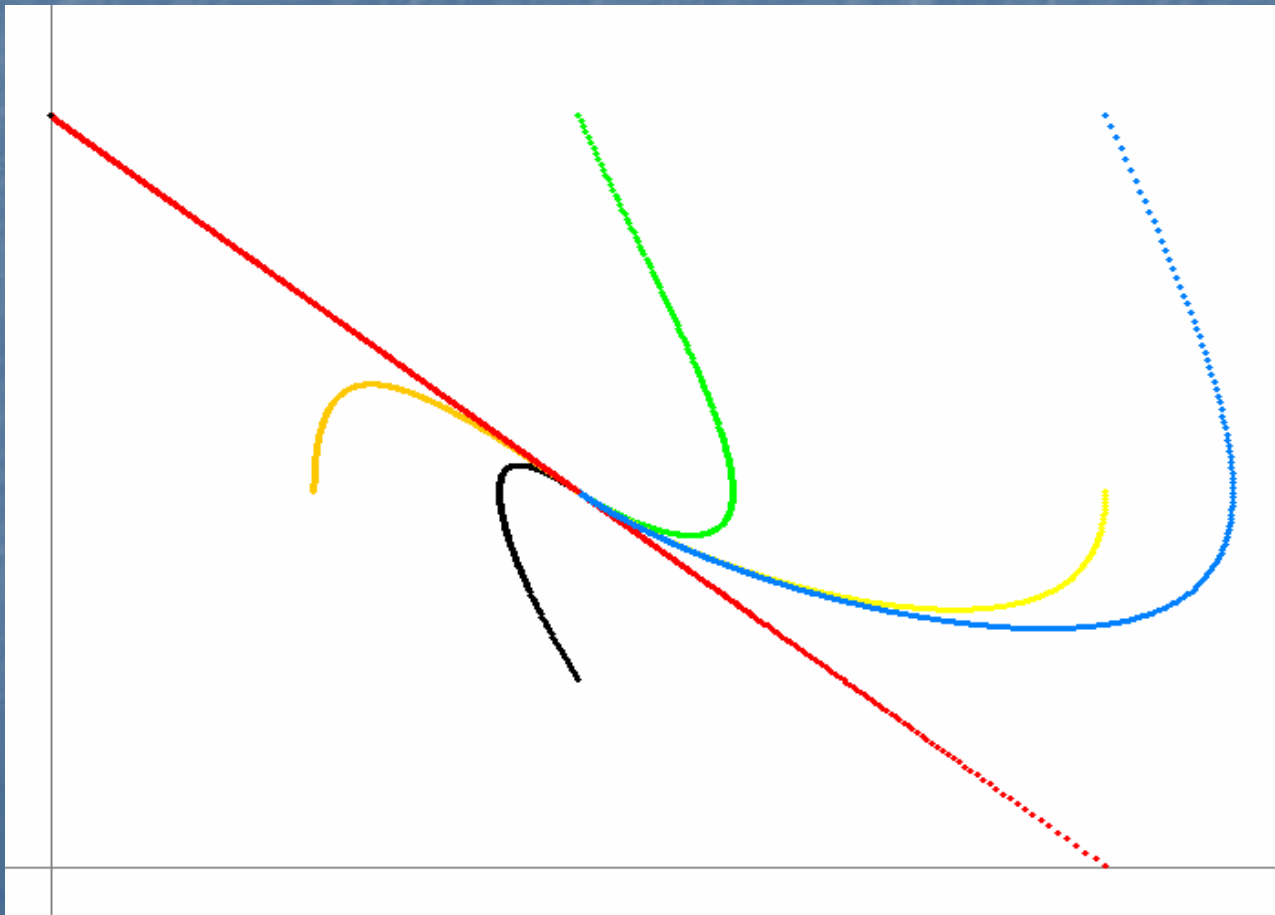
Define  $T = x + S$  and let  $'$  denote differentiation with respect to  $t$ . Clearly,  $T' = x' + S' = 1 - T$  so  $T(t) = 1 + (T(0) - 1)e^{-t}$  and solutions to (Ch) asymptotically approach the invariant unit simplex  $\Sigma = \{(x, S) : x + S = 1\}$ .

If  $m < 1$  then  $x' < 0$  so the equilibrium  $(x, S) = (0, 1)$  is a global attractor, i.e., the organism dies out. If  $m > 1$  then the  $x$ -nullcline is the horizontal line  $S = a/(m - 1)$ . Define  $\lambda = a/(m - 1)$  and note that  $x' > 0$  if  $S > \lambda$ .  $\lambda$  is called the *break-even concentration* because it is the minimum for  $S$  so that  $x$  will grow. Assume that  $\lambda < 1$ .



# Model Analysis

When  $m > 1$  and  $\lambda < 1$ , the equilibrium  $(0, 1)$  is a saddle and  $E = (1 - \lambda, \lambda)$  is globally stable. If  $m = 3$  and  $a = 1$  then  $E = (.5, .5)$ .



# Competition

Assume two organisms  $x_1$  and  $x_2$  compete for the common nutrient  $S$ . The system of o.d.e's becomes:

$$x_1' = \frac{m_1 S x_1}{a_1 + S} - x_1$$

$$x_2' = \frac{m_2 S x_2}{a_2 + S} - x_2$$

$$S' = 1 - S - \frac{m_1 S x_1}{a_1 + S} - \frac{m_2 S x_2}{a_2 + S}.$$

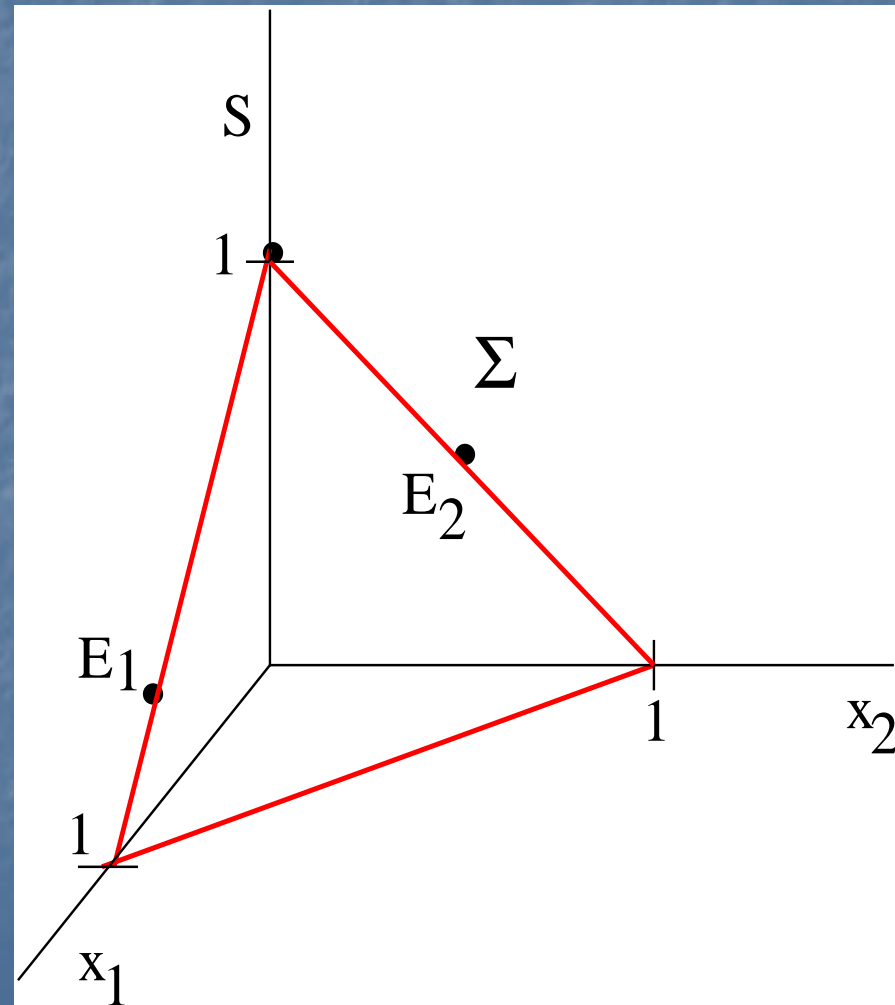
Solutions approach the simplex

$S + x_1 + x_2 = 1$ . If  $m_i > 1$  and

$\lambda_i = a_i / (m_i - 1) < 1$  then the

equilibria are  $(0,0,1)$ ,  $E_1 = (1 - \lambda_1, 0, \lambda_1)$

and  $E_2 = (0, 1 - \lambda_2, \lambda_2)$ .





# Competition

Since  $S = 1 - x_1 - x_2$  on the attracting simplex  $\Sigma$ , the following 2-dim. system describes the behavior on  $\Sigma$  where  $x_1 + x_2 \leq 1$ :

$$x_1' = x_1 \left[ \frac{m_1 (1 - x_1 - x_2)}{a_1 + 1 - x_1 - x_2} - 1 \right]$$

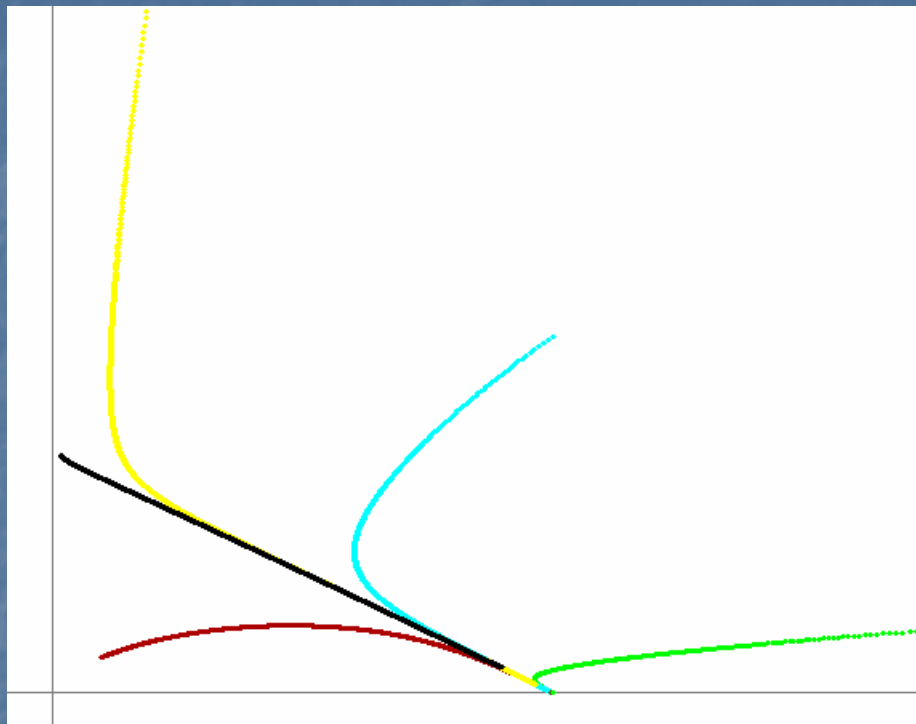
$$x_2' = x_2 \left[ \frac{m_2 (1 - x_1 - x_2)}{a_2 + 1 - x_1 - x_2} - 1 \right]$$

Using topological results like the Poincaré-Bendixson theorem and the Butler-McGehee lemma, it follows that:

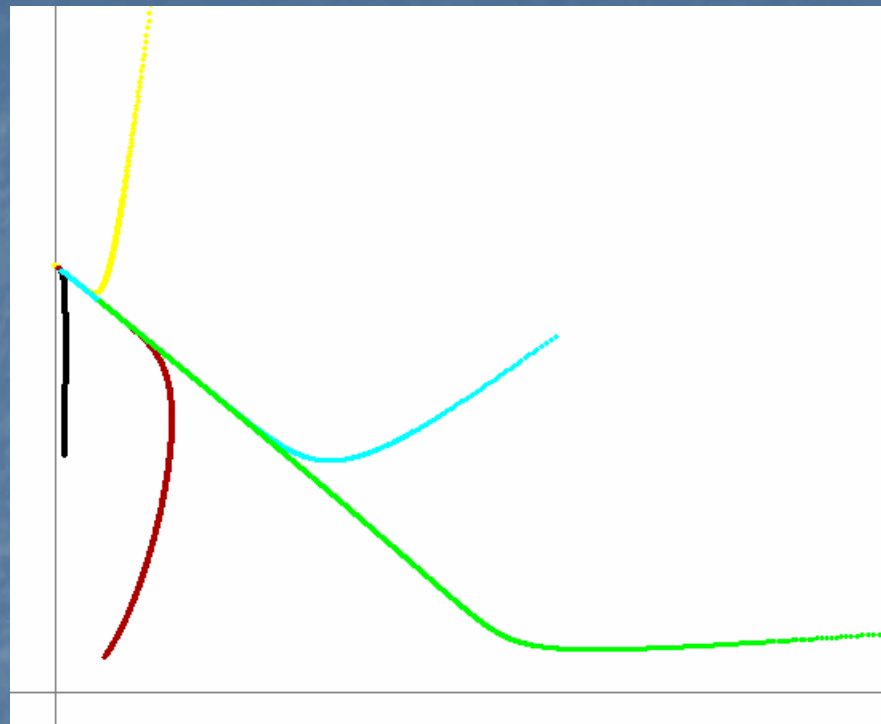
**Theorem** (Hsu, Hubbell, and Waltman, 1977). If  $m_i > 1$  and  $0 < \lambda_1 < \lambda_2 < 1$  then each solution with  $x_i(0) > 0$  has  $S(t) \rightarrow \lambda_1$ ,  $x_1(t) \rightarrow 1 - \lambda_1$  and  $x_2(t) \rightarrow 0$ .

# Competition

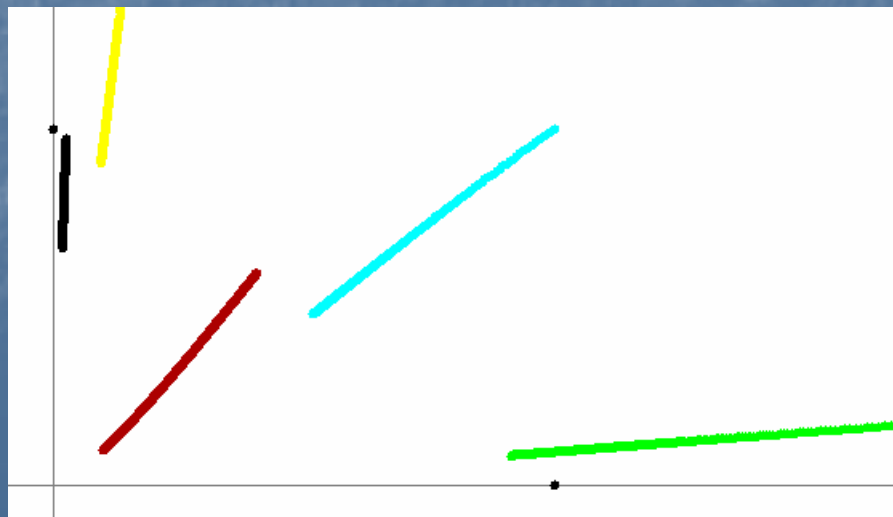
$\lambda_1 = .5, \lambda_2 = .667$



$\lambda_1 = .5, \lambda_2 = .4$



$\lambda_1 = .5, \lambda_2 = .5$



$x_1, x_2$  on  $\Sigma$

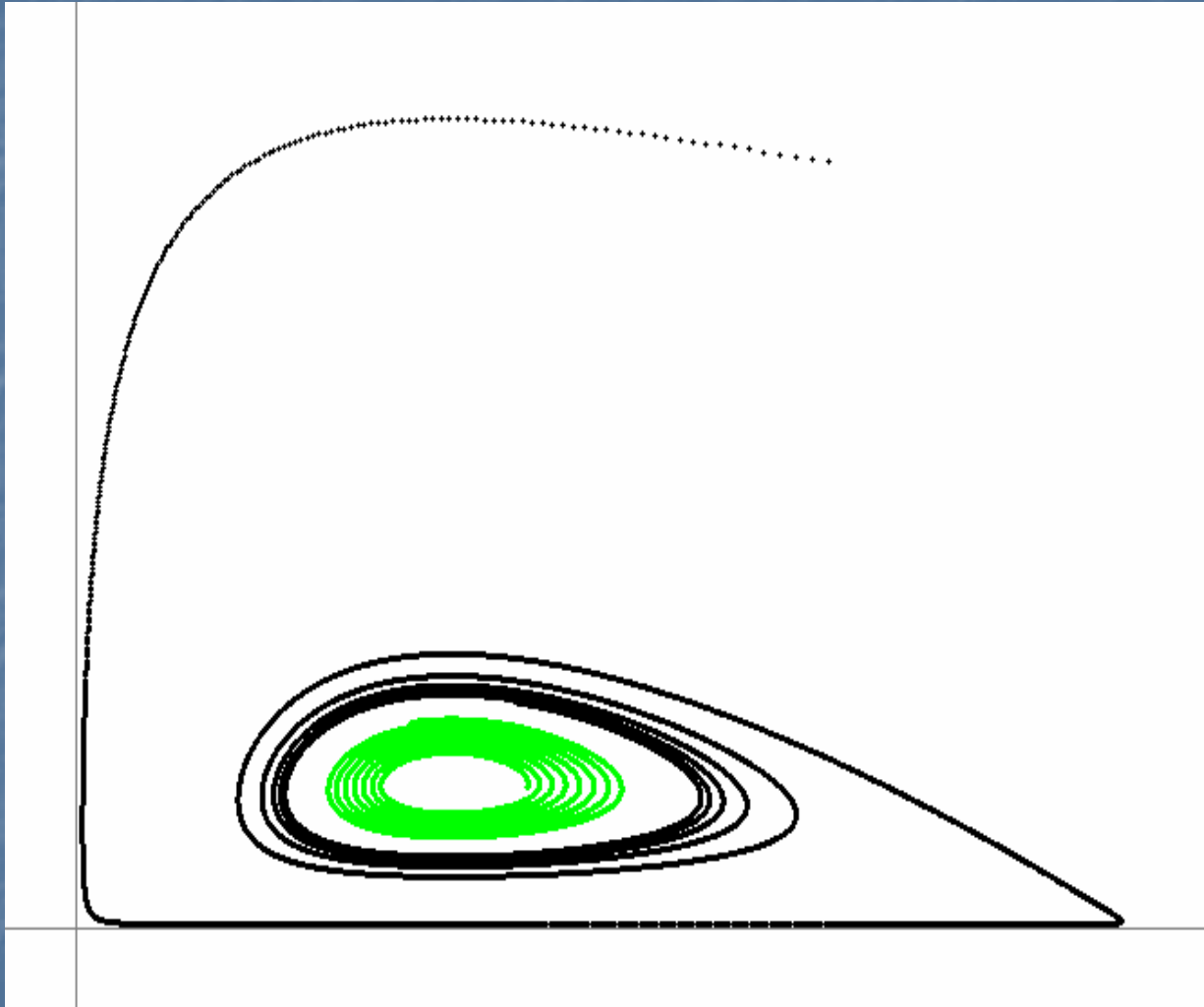
# Prey-Predator

If  $x_1$  is a prey and  $x_2$  is a predator with a Michaelis-Menton interaction term then the system becomes:

$$\begin{aligned}x_1' &= \frac{m_1 S x_1}{a_1 + S} - \frac{m x_1 x_2}{a + x_1} - x_1 \\x_2' &= \frac{m_2 S x_2}{a_2 + S} + \frac{m x_1 x_2}{a + x_1} - x_2 \\S' &= 1 - S - \frac{m_1 S x_1}{a_1 + S} - \frac{m_2 S x_2}{a_2 + S}.\end{aligned}$$

Solutions approach the simplex  $\Sigma$  where  $S + x_1 + x_2 = 1$ . A Hopf bifurcation occurs in  $\Sigma$  at  $a_1 \approx 0.35$ ,  $m_1 = 2$ ,  $a_2 = 0.5$ ,  $m_2 = 0.05$ ,  $a = 0.25$  and  $m = 2$  resulting in a globally stable periodic solution.

# Prey-Predator



$$a_1 = 0.3$$

# References

- L. Edelstein-Kesket, *Mathematical Models in Biology*, Random House, New York, 1988.
- S.B. Hsu, S.P. Hubbell and P. Waltman, A mathematical theory for single nutrient competition in continuous cultures of microorganisms, *SIAM Jour. Appl. Math.* **32**, 366-383, 1977.
- H.L. Smith and P. Waltman, *The Theory of the Chemostat: Dynamics of Microbial Competition*, Cambridge University Press, 1995.